

# **How to Design a Streamlined Macro-System With Autonomous Micro-Units?**

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# 1. The Prevailing System Thoughts

- ❑ The failure of fragmented functional design
- ❑ The emergence of more and more system-oriented managerial tools and methods
- ❑ The rapid development of information technology
- ❑ Customer-oriented competition calls for boundaryless organizations

## 2. Why Need the Autonomous Units

### 2.1. The Practitioner's Challenges

- ❑ Violent environmental turbulences and the contingency required for real operations
- ❑ The importance of adaptability, flexibility, and learning ability
- ❑ New forms of organizational structure, ex, modular organizations, loosing coupling organizations

## 2. Why Need the Autonomous Units

### 2.2. The Academic Development

- ❑ Organizations as stable orders vs. continuously changing emergents, (Poole and Van De Ven, 1989)
- ❑ Equifinality: functional equivalence in organization design (Gresov and Drazin, 1997)
- ❑ The need for a responsive and distinctive system (Orton and Weick, 1990)

**But, how to design the system as a whole  
while maintaining the adaptability and  
flexibility of micro-level units**

**That is .....**

**How to streamline the activities of  
autonomous units?**

# 3. Conceptual Design of A Streamlining Systems with Autonomous Units

## 3.1. Non-synchronous System Type

Units act with no coordination;

➡ Autonomous units may conflict each other

## 3.2. Synchronous System Type

Units act at the same pace at the same time

➡ System can act as a whole but units' autonomy is lost

# 3. Conceptual Design of A Streamlining Systems with Autonomous Units

## 3.3. Asynchronous System Type

Units act at the same pace and act at different time

➡ Units can harmonize their activities with their autonomy to decide most appropriate timing for them to act

➡ A streamlining design of autonomous units

## 3.4. Designing guideline

Each unit is set to operate toward the synchronized goals, but it keep its autonomy to determine appropriate timing to take actions

## **4. Using System Dynamics As A Platform to Coordinate Units**

### **4.1. Rationality of Using SD as the Platform**

- Focus on the time varying behaviors, rather than any artificial boundaries
- System models built on the micro interactions with information feedback theory
- Emphasis on the systemic performance
- Simulation tools and methodology for system design under various scenarios



## 4. Using System Dynamics As A Platform to Coordinate Units

### 4.2. Unexplored Region of SD as to the Coordination Design

- ❑ SD focus mostly on the policy design of a few rates and actions, rather than the relationships of all decision points.
- ❑ SD designs the system as a whole, but often neglects the distinctive nature of micro-level units and related relationships
- ❑ SD development is focus more on the information phase of decision rules, the action phase of rates and flows receives attentions slightly

# 5. Modelling a Streamlining System with Autonomous Units

## 5.1. Related Concepts, Theory, and Research

- ❑ Equifinality and Creativity concept (Gresov and Drazin, 1997; Fritz, )
- ❑ Theory of Constraints and DBR design  
(Goldratt and Cox, 1992; Srikanth and Podzunas, 1990; Goldratt, 1987)
  - ➡ Core concepts to set a systemwide goals as the basis for critical rates
- ❑ Synchronous flow-based design of SD high leverage design  
(Young, Tu, and Tseng, 2002)
  - ➡ A SD-based and flow-based design process to synchronize the actual output of each rates

# 5. Modelling a Streamlining System with Autonomous Units

## 5.2. Steps to Design

- ❑ Decide the “drum” to be the basis of rates’ operational pace; That is, find out the most critical information source
- ❑ Apply the synchronization process to set the original pace for each rates (reference to Young, Tu, and Tseng, 2002)
- ❑ Create levels for each rates to identify and calculate the required workload
- ❑ Formulate decision rules for each rates based on the related level created

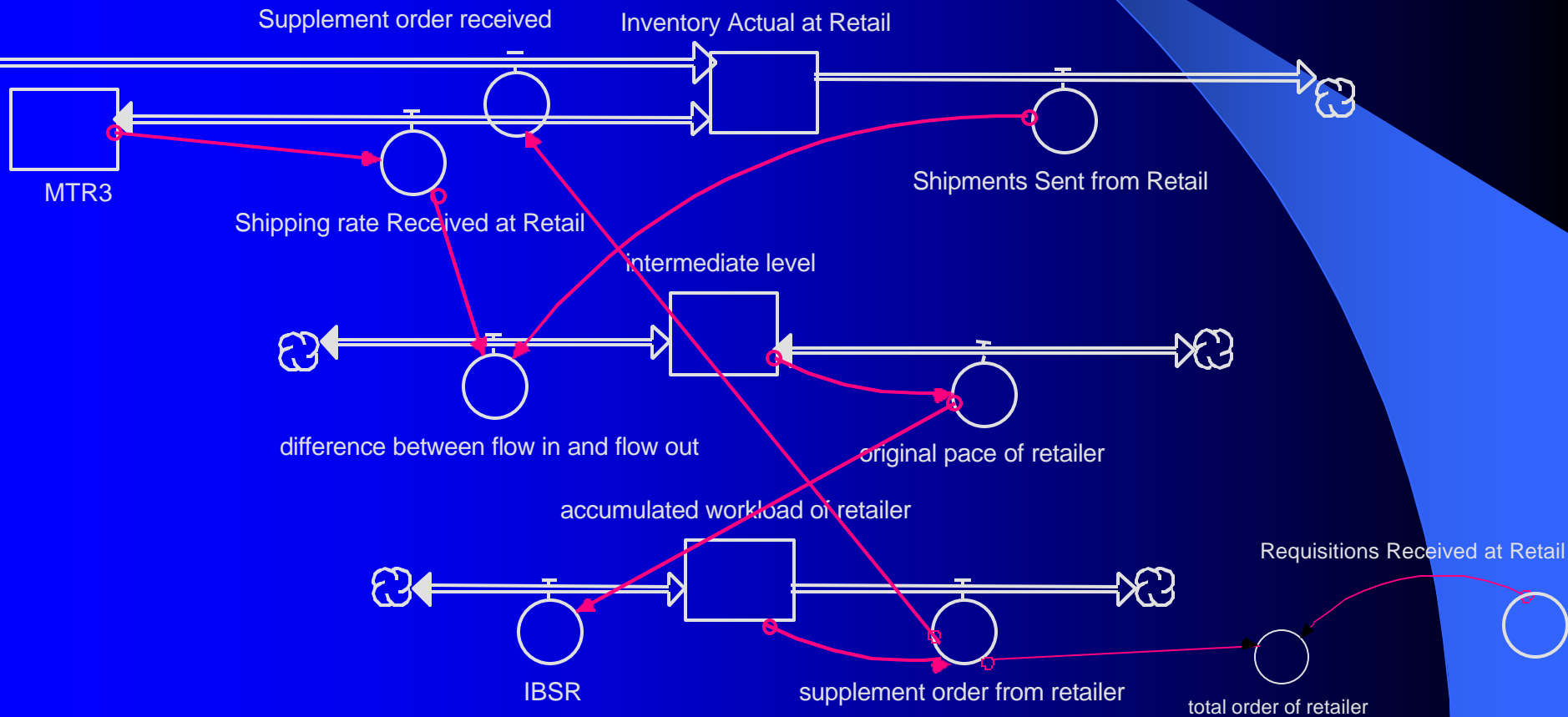
# 6. Example: A Supply Chain System

## 6.1. Descriptions of the Experimental Model

- ❑ Forrester(1961): Industrial dynamics
- ❑ The so-called bullwhip effect or forrester effect
- ❑ 3 major decisions: inventory policies of retailer, distributor, and manufacturer
- ❑ The most critical information source: customer's order

# 6. Example: A Supply Chain System

## 6.2. Part of the Streamlining Model



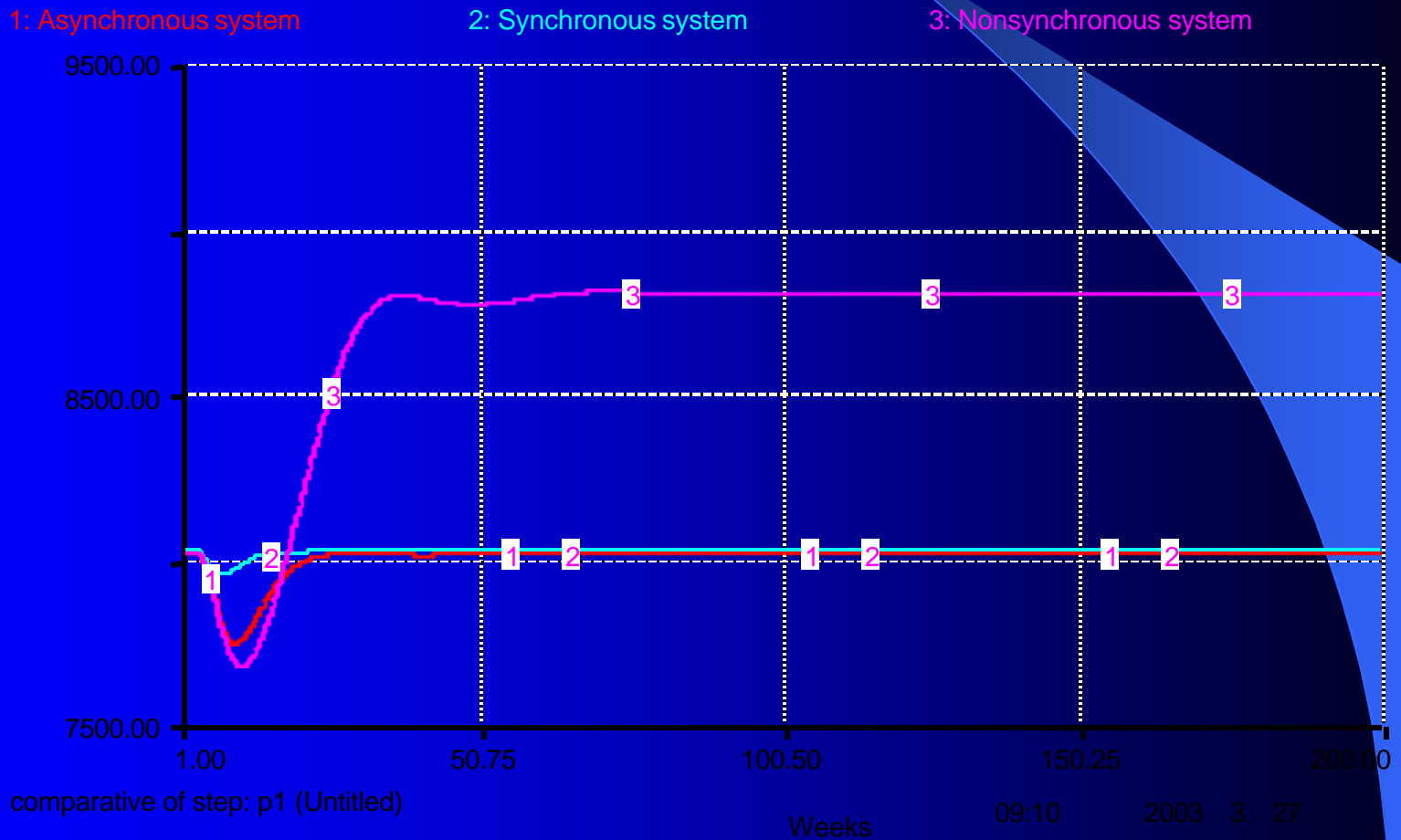
# 6. Example: A Supply Chain System

## 6.3. Simulation Results

- ❑ Non-Synchronous System: original model built by Forrester (1961)
- ❑ Synchronous System: a redesigned model with the synchronous method developed in previous paper
- ❑ Asynchronous System: streamlining the system with each rate to adjust its own action based on the synchronized pace

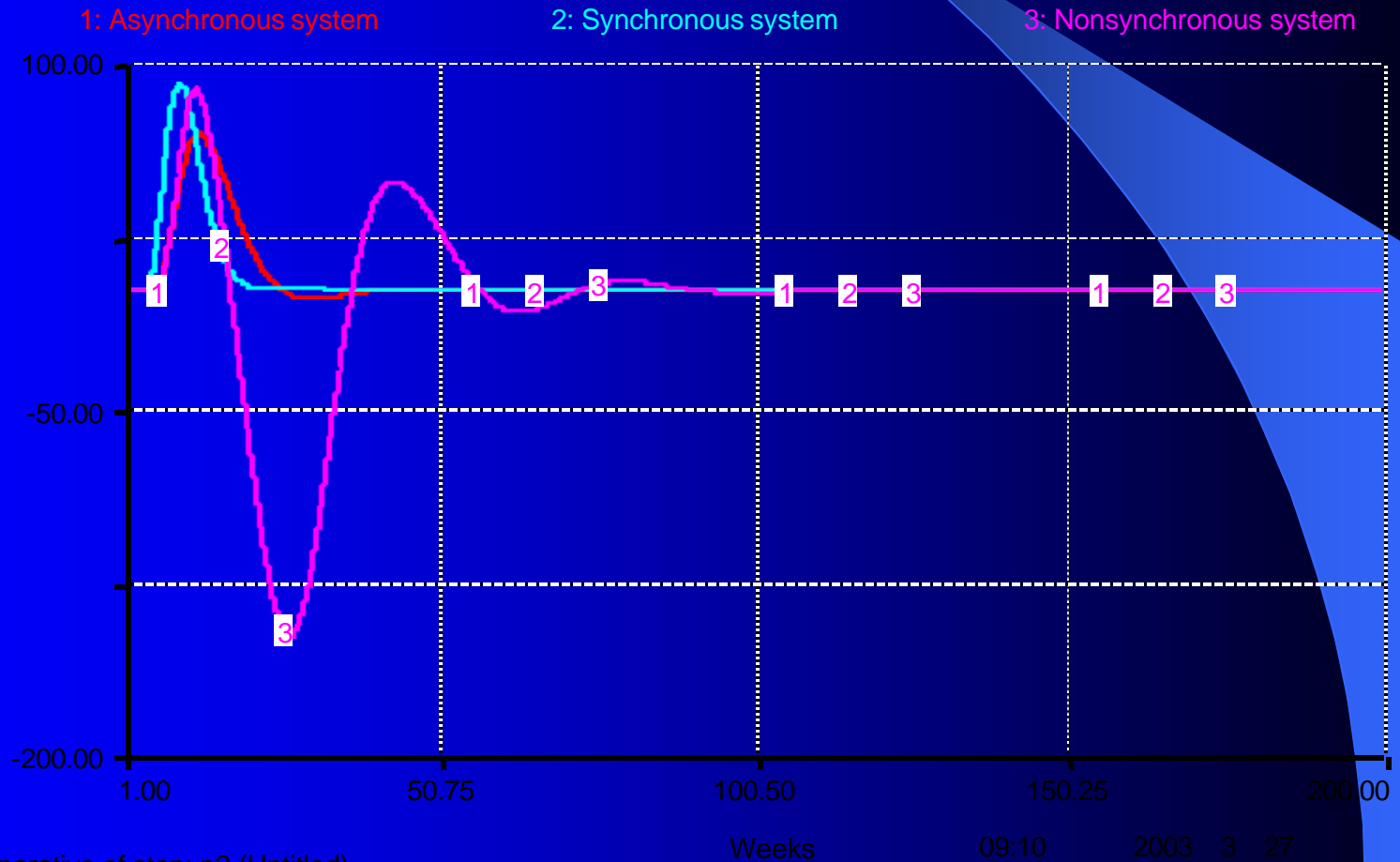
## 6.3.1. Customer Order: 1000+step(100, 3)

(1) Comparative behaviors of retailer's inventory



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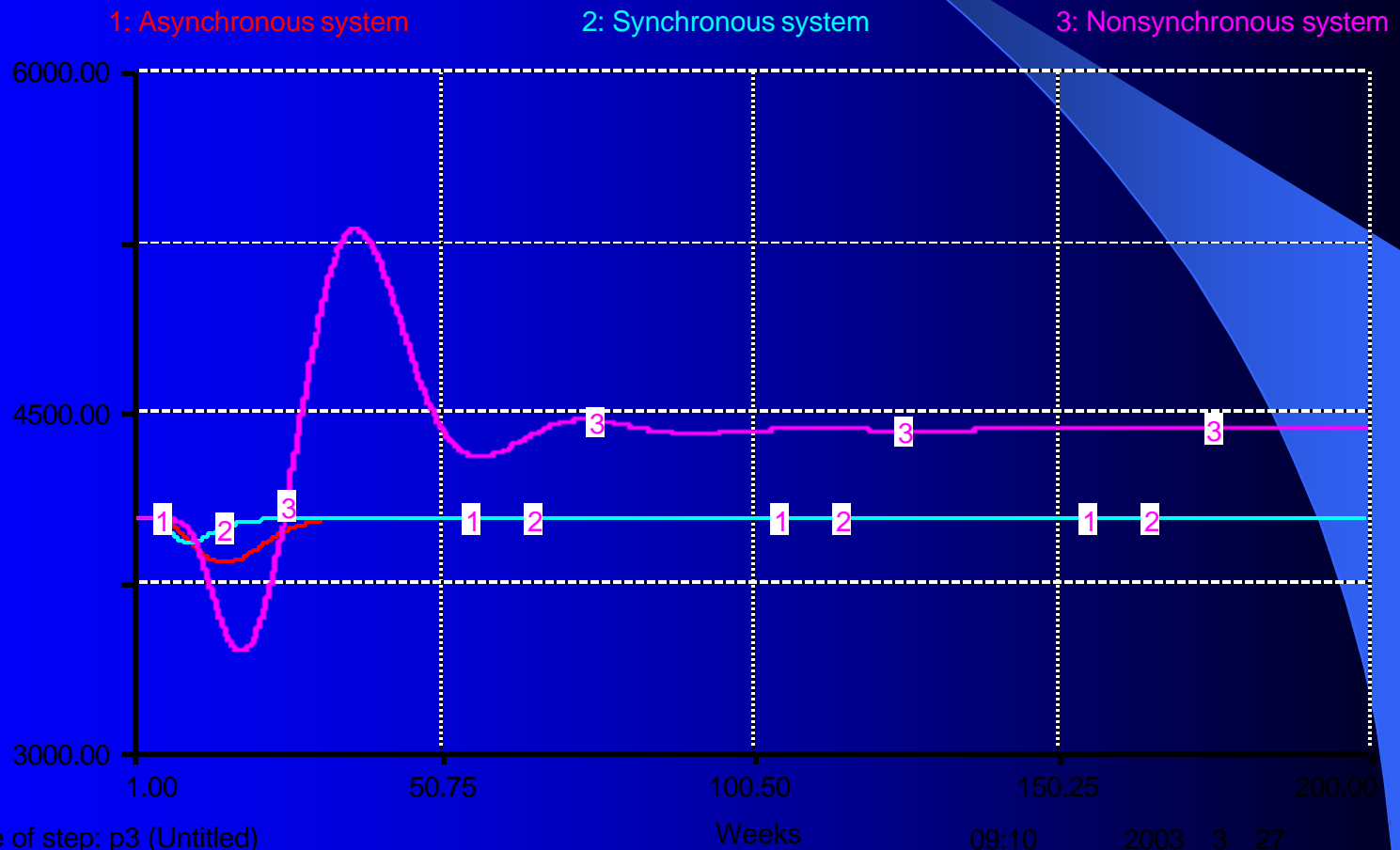
(2)Comparative behavior of distributor's inventory





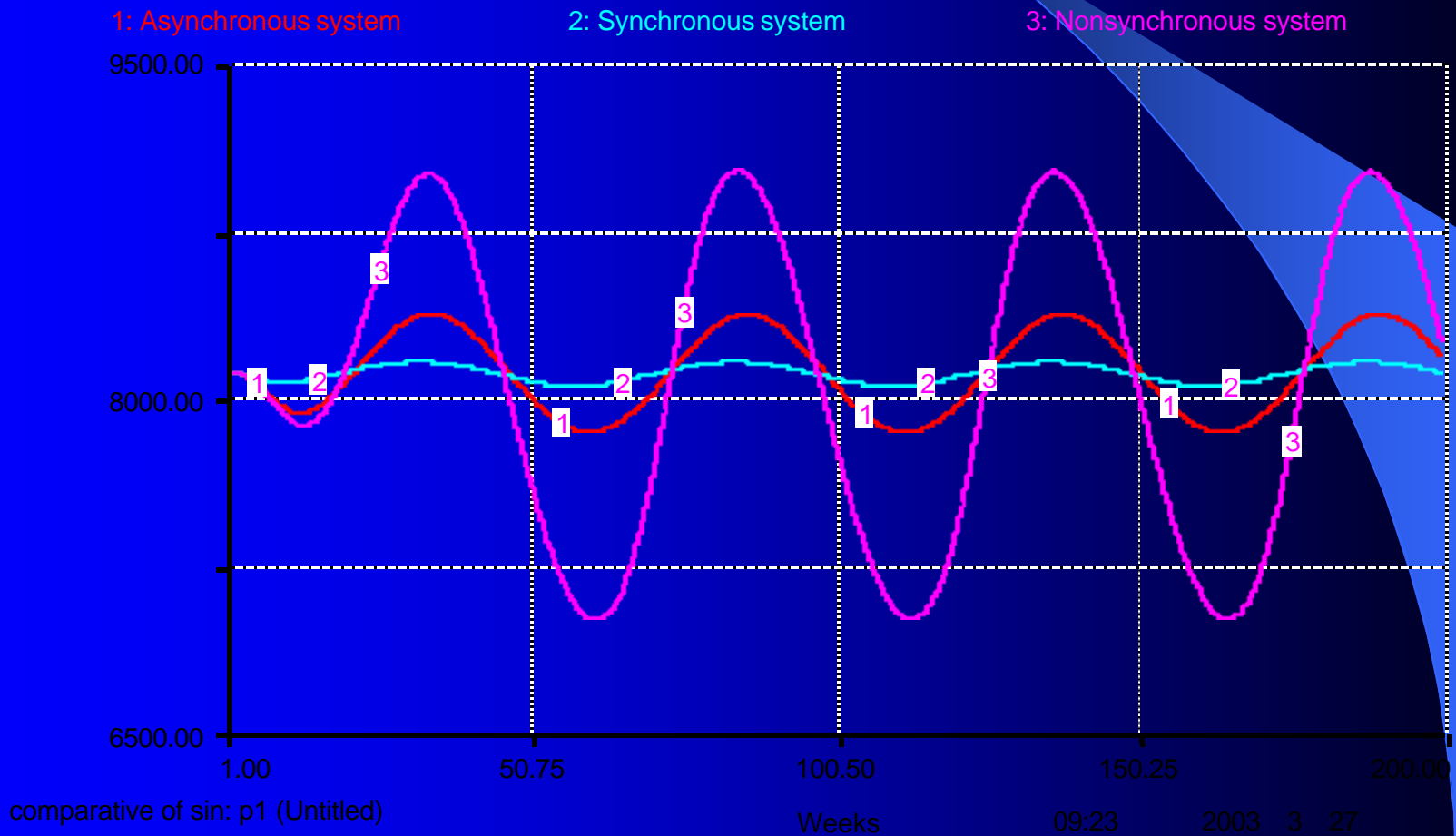
## 6.3.1. Customer Order: 1000+step(100, 3)

(3)Comparative behavior of manufacturer's inventory



## 6.3.2. Customer Order: $1000+100*\sin(2*\text{Pi}*\text{Time}/52)$

(1) Comparative behavior of retailer's inventory



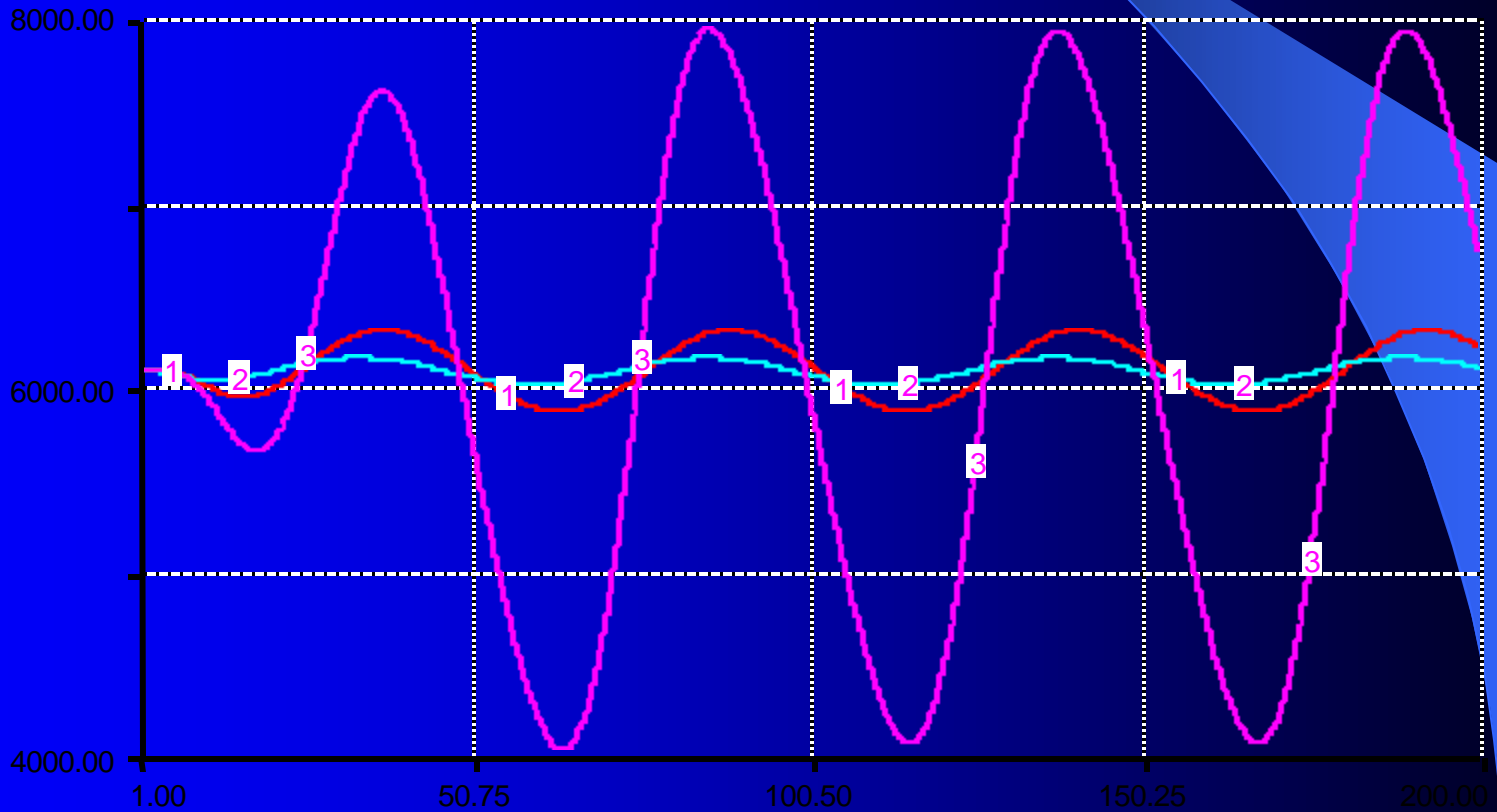
## 6.3.2. Customer Order: $1000+100*\sin(2*\text{Pi}*\text{Time}/52)$

(2)Comparative behavior of distributor's inventory

1: Asynchronous system

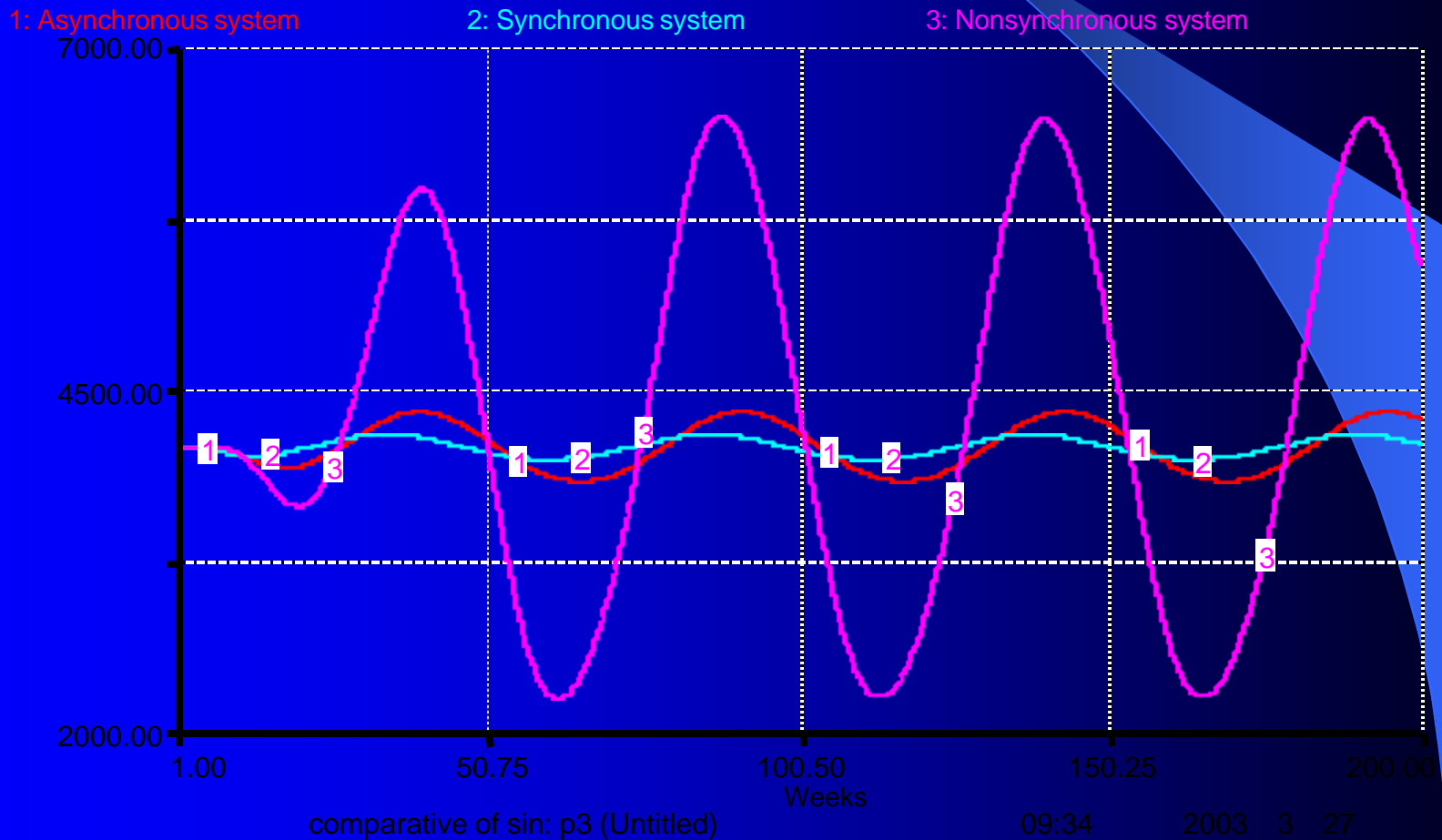
2: Synchronous system

3: Nonsynchronous system



## 6.3.2. Customer Order: $1000+100*\sin(2*\text{Pi}*\text{Time}/52)$

(3)Comparative behavior of manufacturer's inventory



### 6.3.3. Summary

- ❑ Both synchronous and asynchronous systems work much better than the original non-synchronous model
- ❑ Though armed with less control over the rates, asynchronous systems can behave as good as the central-controlled synchronous systems.

**Customer Order:  $1000+100*\sin(2*\text{Pi}*\text{Time}/52)$**

	Average inventory of retailer	Average inventory of distributor	Average inventory of manufacturer
Non-syn.	8560	7109	5613
synchronous	8124	6113	4103
Asynchro.	8254	6215	4209

## 7. Discussion and Conclusion

- ❑ As environments call for more and more attention on the boundaryless systems, the trade-off design of sub-units' autonomy and systemic performance is quite important
- ❑ Asynchronous systems leave a room for rates to decide the way to implement the assigned goals, while streamlining those goals at macro-system level
- ❑ Not only adaptive to environmental changes, autonomous units have more possibilities to emerge better systemic behavior as a whole (tangible and intangible)
- ❑ Other methods and tools can be used to search various policy sets for the autonomous units

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